



Numerical Modeling of Copepod's behavior in Turbulent Flows

Hamidreza Ardestiri

Laboratoire de Mécanique de Lille - UMR 8107

Laboratoire d'Océanologie et de Géoscience - UMR 8187



Mechanical Engineering



UNIVERSITÉ D'ARTOIS



Thesis title: Dynamics of Copepods in Turbulent Flows

Advisor: François SCHMITT, DR HDR CNRS, LOG (UMR 8187)

Participants:

Co-advisor: Enrico CALZAVARINI, MdC, Université de Lille 1

International collaborator: Federico TOSCHI, Full Professor, Technical University of Eindhoven

Local collaborator: Sami SOUSSI, Full Professor, Université de Lille 1

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Doctoral Schools SMRE, Laboratoire d'Océanologie et de Géoscience ([LOG](#)), UMR 8187

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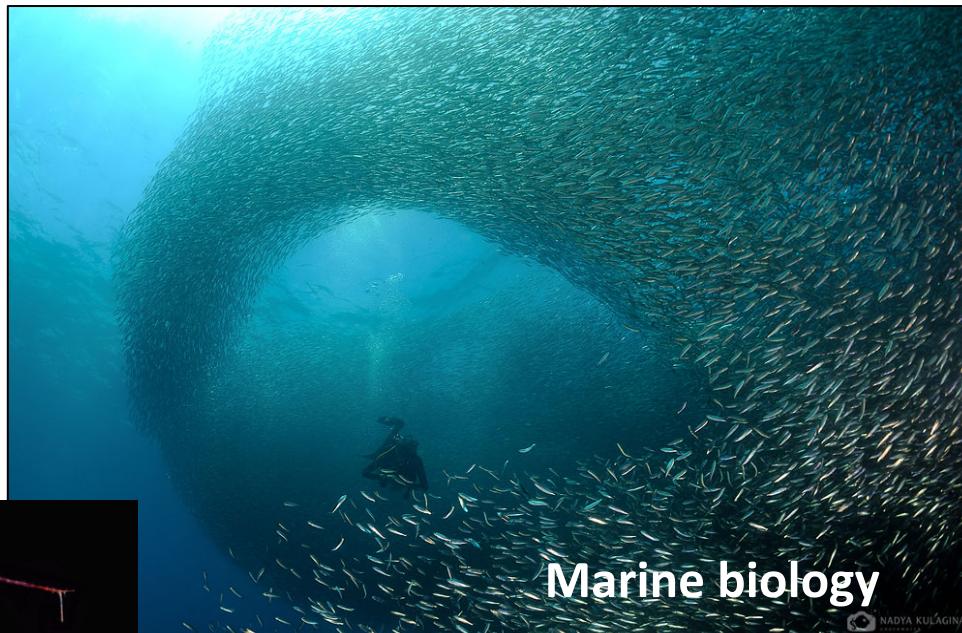
Ministry of higher education and research fellowship, Bourse President
Lille 1 for interdisciplinary subjects

Outline:

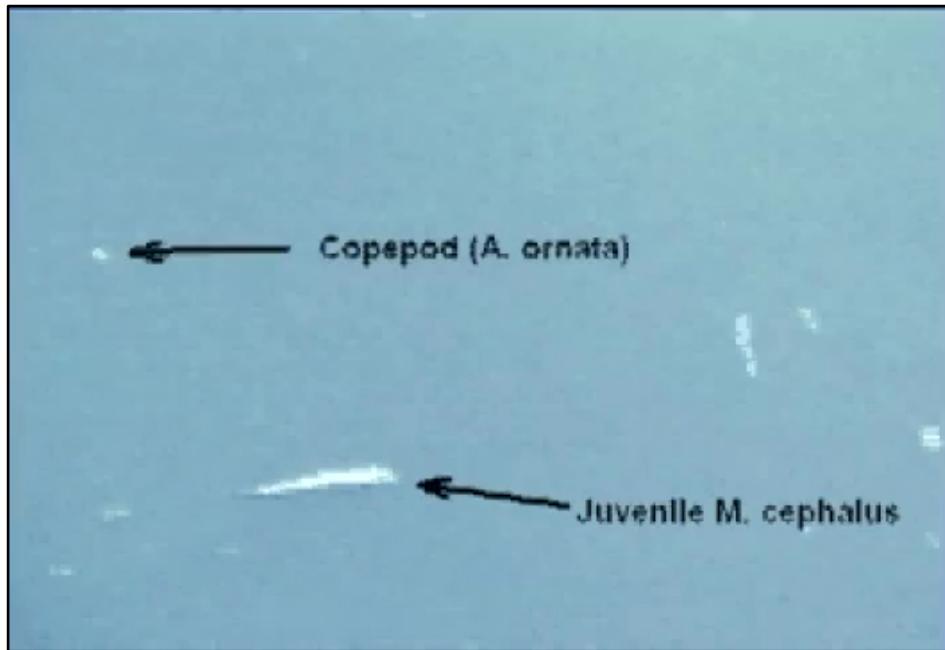
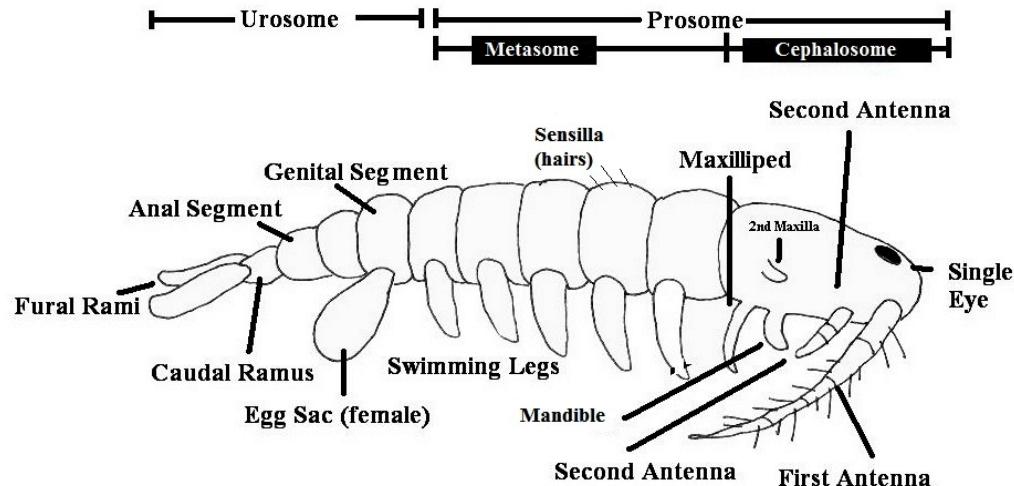
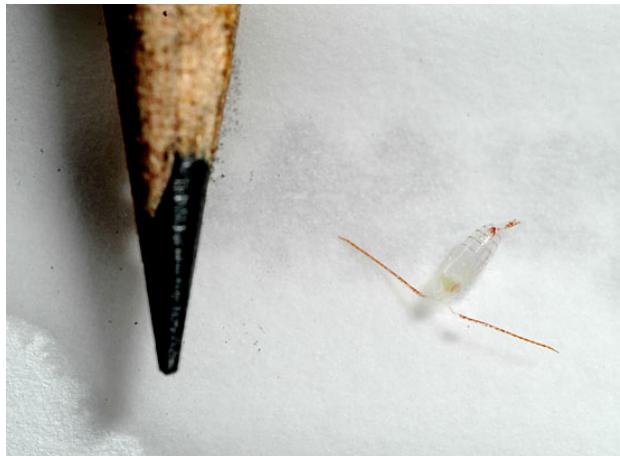
- Motivation
- Introduction to Copepods
- Methods
- Analysis
- Perspective

Motivation!

- Important link in the food chain
- Most numerous crustaceans in the ocean
- Fishery Industry
- Better understanding the oceanic life



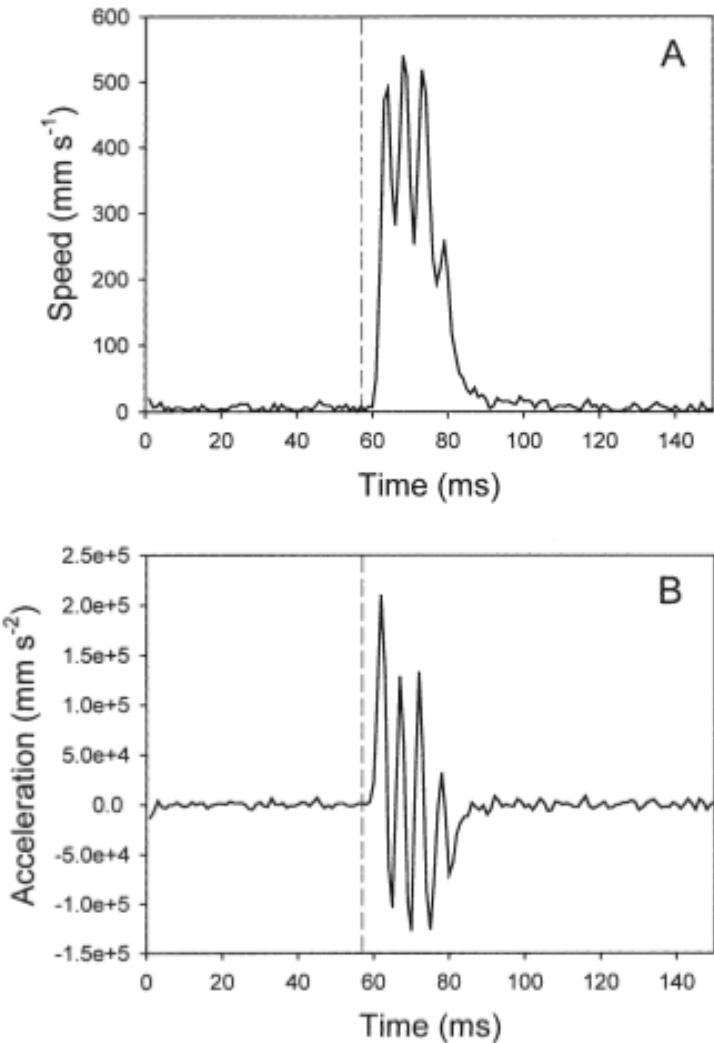
What are copepods?



Copepods cultures at LOG Lab in Wimereux

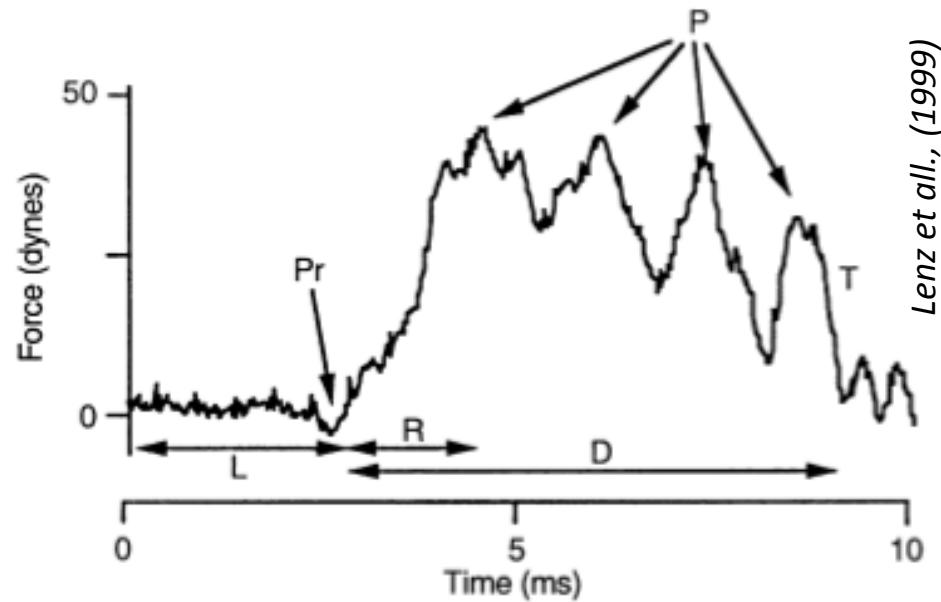
Response to Stimulus

Acartia tonsa: The stimulus occurred 3 (ms) before the initiation of the escape response (dashed line)



Buskey et al., (2002)

Response parameters



Lenz et al., (1999)

Undinula vulgaris giesbrechti response

L: latency to forward propulsion

Pr: preparation

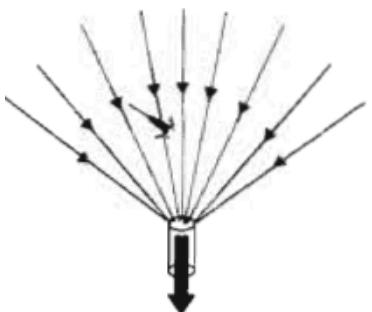
R: rise

P: force peaks

D: kick (power strokes) duration

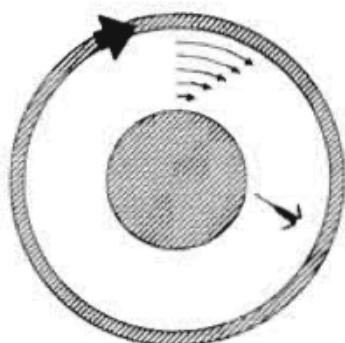
T: termination

Component of the flow?



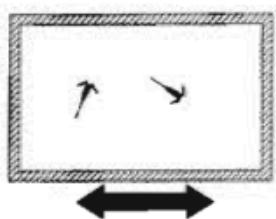
Siphon flow

- longitudinal deformation
- acceleration



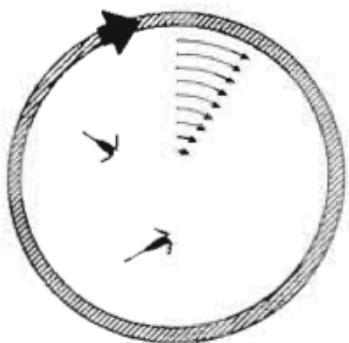
Couette device

- shear deformation
- acceleration
- vorticity



Oscillating chamber

- acceleration

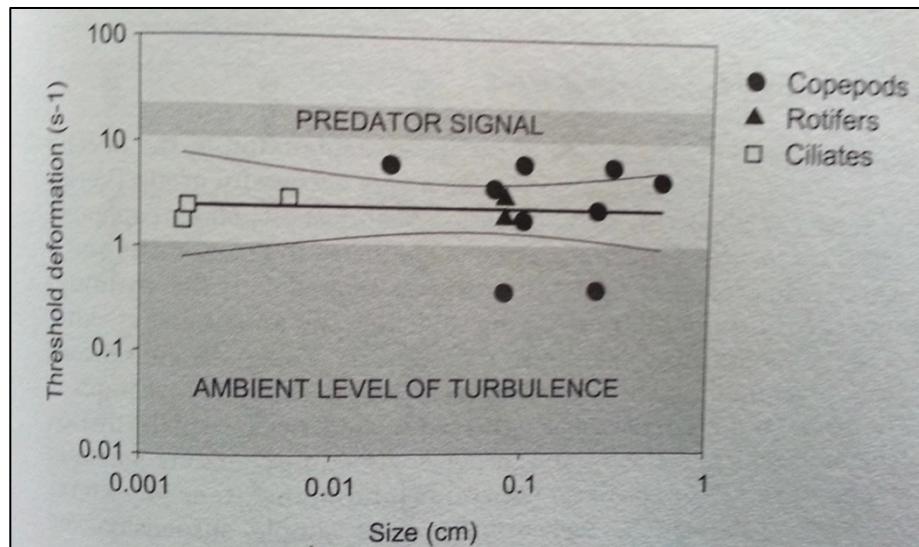


Rotating cylinder

- acceleration
- vorticity

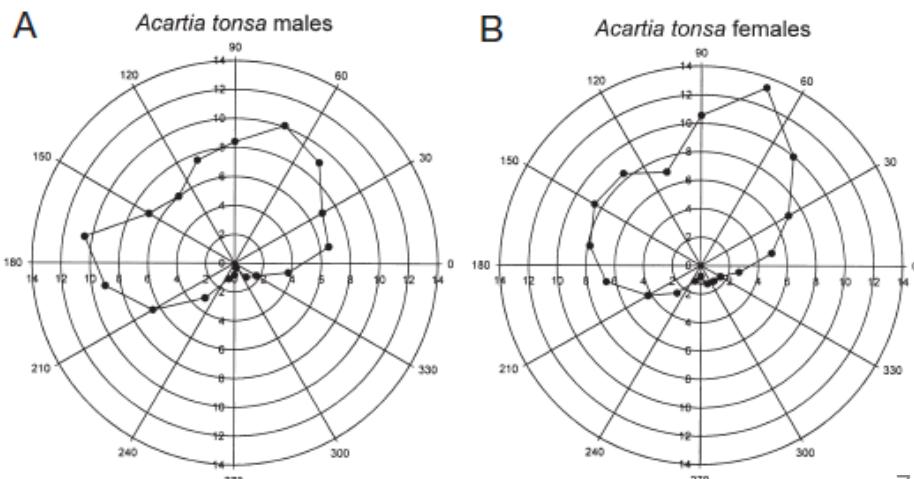
Copepods react to deformation rate

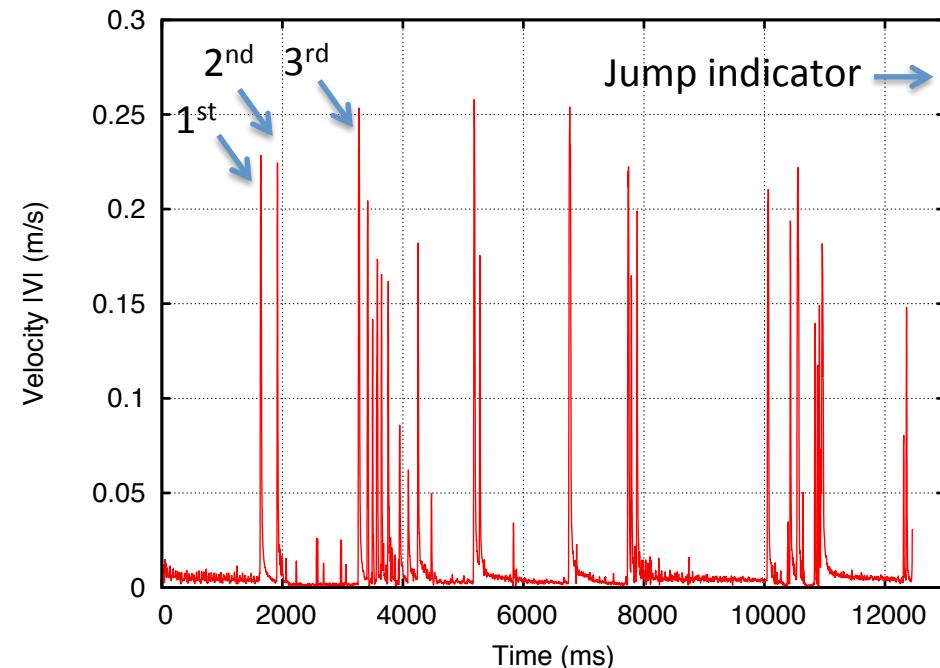
Thresholds



Kiorboe et al., (1999)

Direction of Escape?

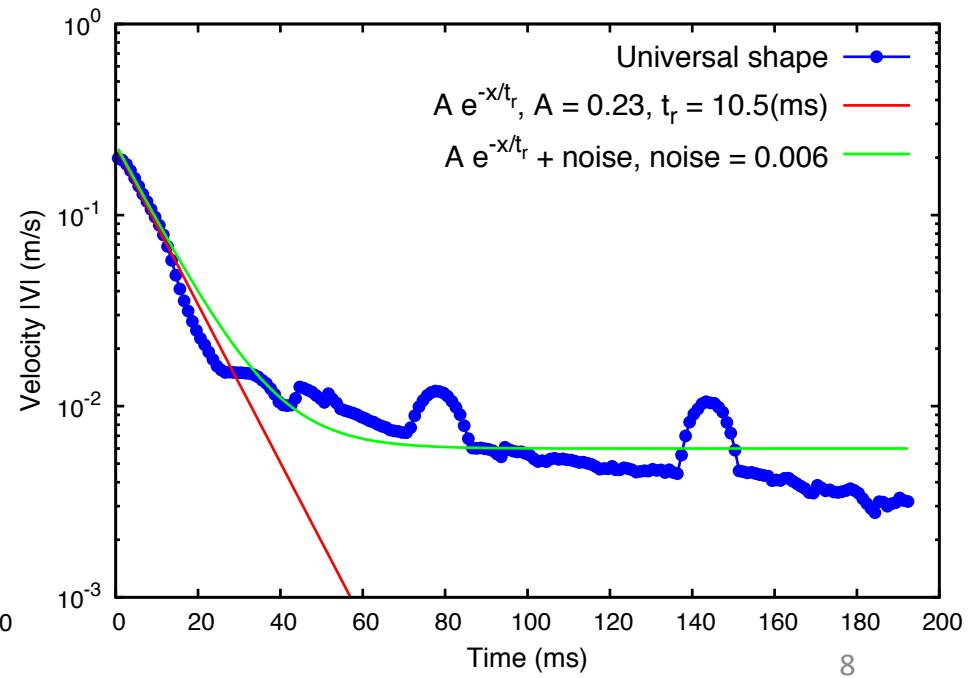
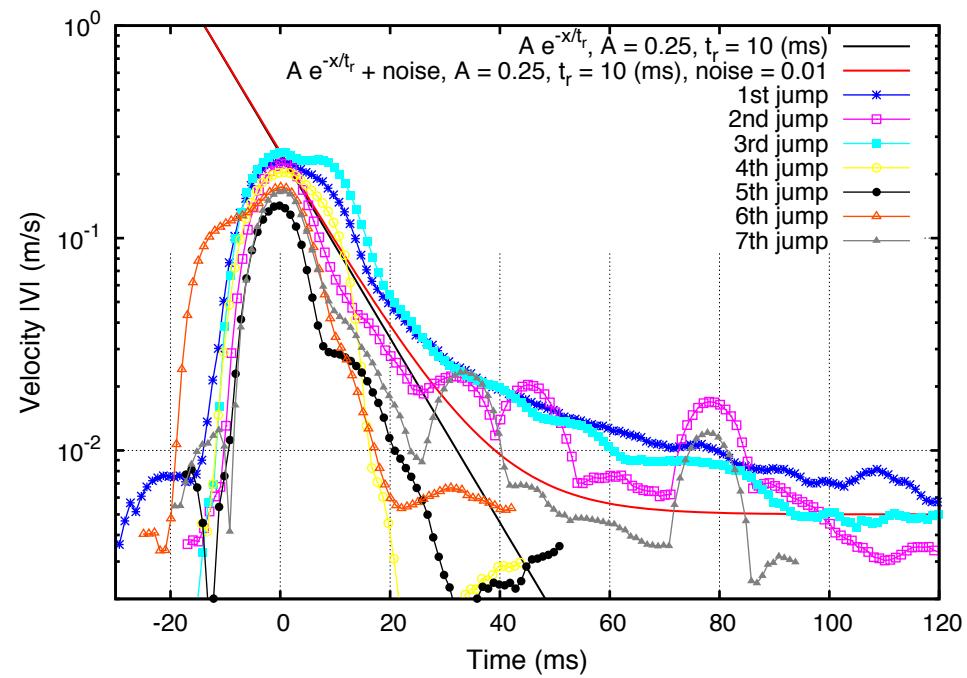




Lagrangian model

Response of copepods in still water,
Data collected by **Ibtissem Benkreddad**
at LOG, Wimereux

Jumps superposed by considering
their peak as a reference.



Lagrangian model

Modified Chlamydomonas model

$$\frac{d\mathbf{x}}{dt} = \mathbf{v} + u_s \mathbf{p}$$

$\left. \begin{array}{ll} \mathbf{v} & \text{Fluid velocity} \\ u_s & \text{Slipping velocity} \\ \mathbf{p} & \text{Direction of motion} \end{array} \right\}$

$$u_s(t) = u_F + u_J e^{-(t-t_0)/\tau_J}$$



Foraging velocity

Jumping velocity

PARAMETER	UNIT	RANGE OF VALUES		VALUE
ν	$m^2 s^{-1}$	$O(10^{-6})$		10^{-6}
ϵ	$m^2 s^{-3}$	10^{-8}	10^{-4}	10^{-6}
η	m	3×10^{-3}	3×10^{-4}	10^{-3}
τ_η	s	10	0.1	1
u_η	ms^{-1}	3×10^{-4}	3×10^{-3}	10^{-3}
Re_λ	-	$O(10^2)$		

Dimensionless control parameters

$$\frac{u_J}{u_\eta} \quad \frac{\tau_J}{\tau_\eta}$$

$$S_{threshold} \times \tau_\eta$$

Properties of the ocean water

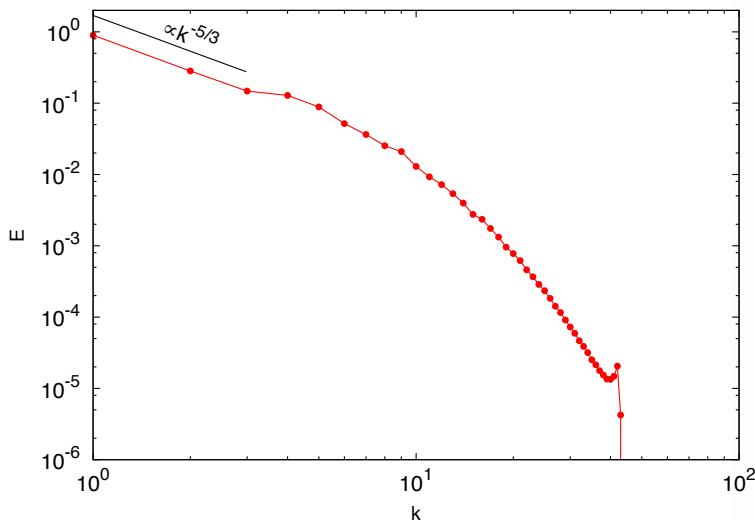
Methods

Eulerian - Lagrangian

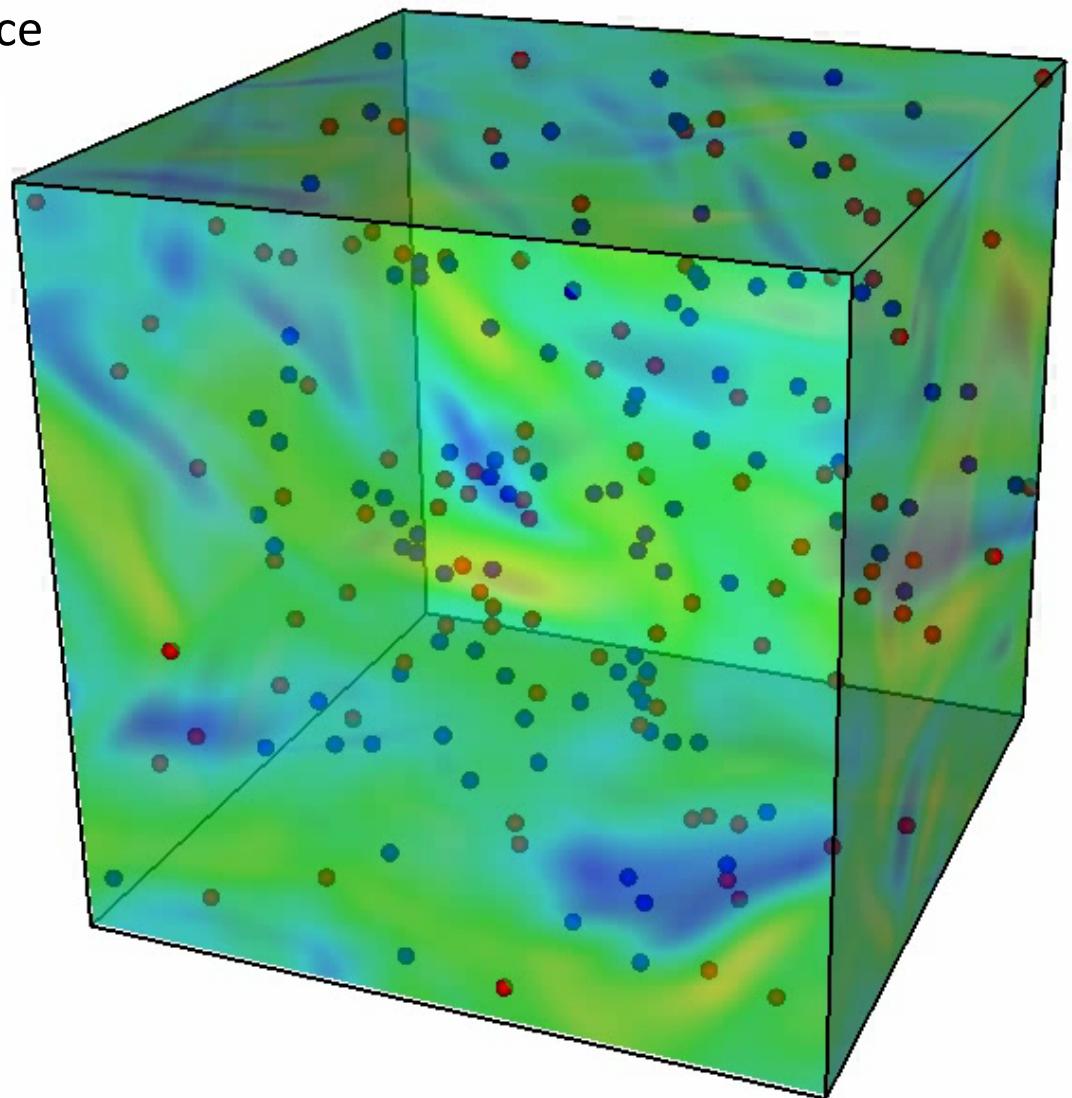
Homogeneous Isotropic Turbulence

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\nabla P + \nu \nabla^2 \mathbf{u}$$

$$\nabla \cdot \mathbf{u} = 0$$

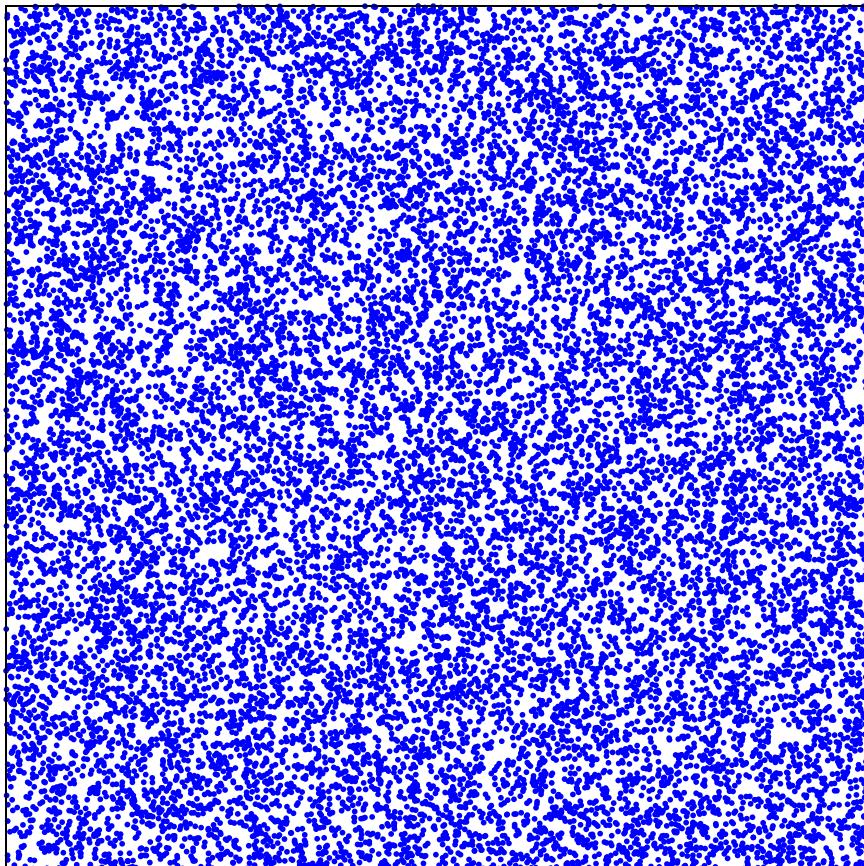


Spectral Method

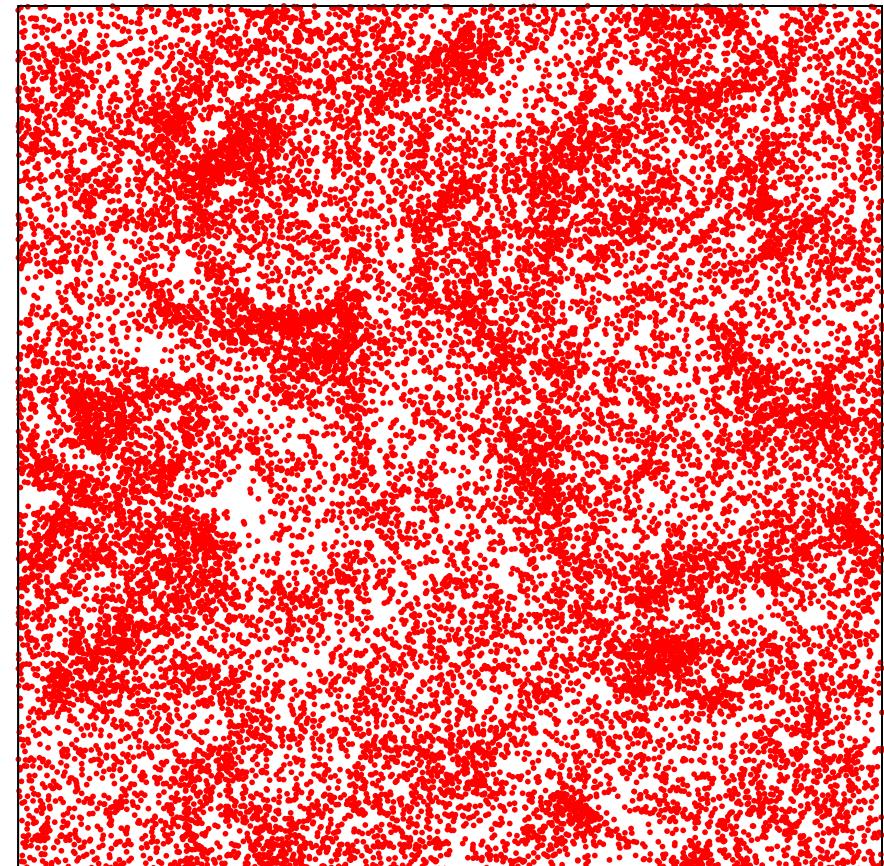


Analysis

Tracers



Copepods



Patchiness

Analysis

Quantifying spatial distribution of the copepods : Fractal dimension D_2

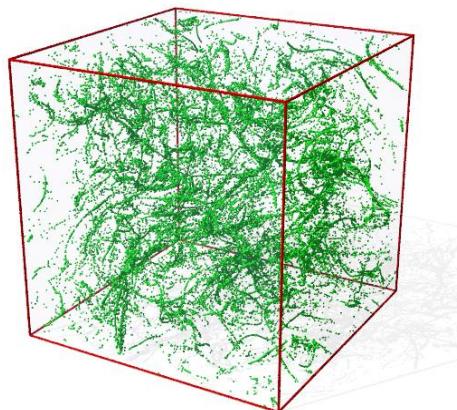
The **Grassberger-Procaccia** Algorithm:

$$\hat{C}(r) = \frac{2}{N(N-1)} \sum_{i < j} \theta(r - |\mathbf{x}_i - \mathbf{x}_j|) \quad \theta(x) \text{ is Heaviside step function}$$

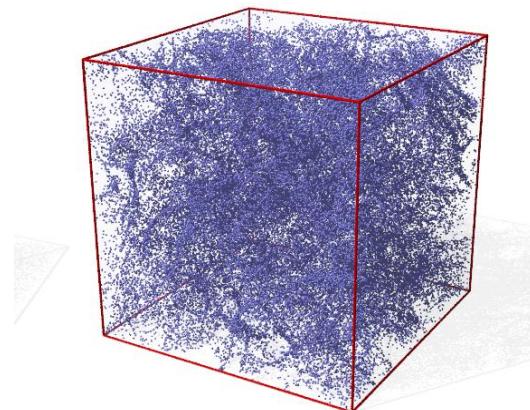
Monotonically decreasing like power law $C(r) \sim r^D$ as $r \rightarrow 0$

Probability to find a couple of particle whose distance is below r

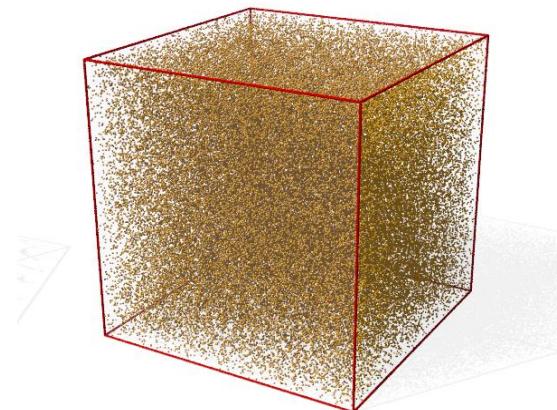
$$D = \lim_{r \rightarrow 0} \frac{\log C(r)}{\log r}$$



$$D_2 \approx 1$$



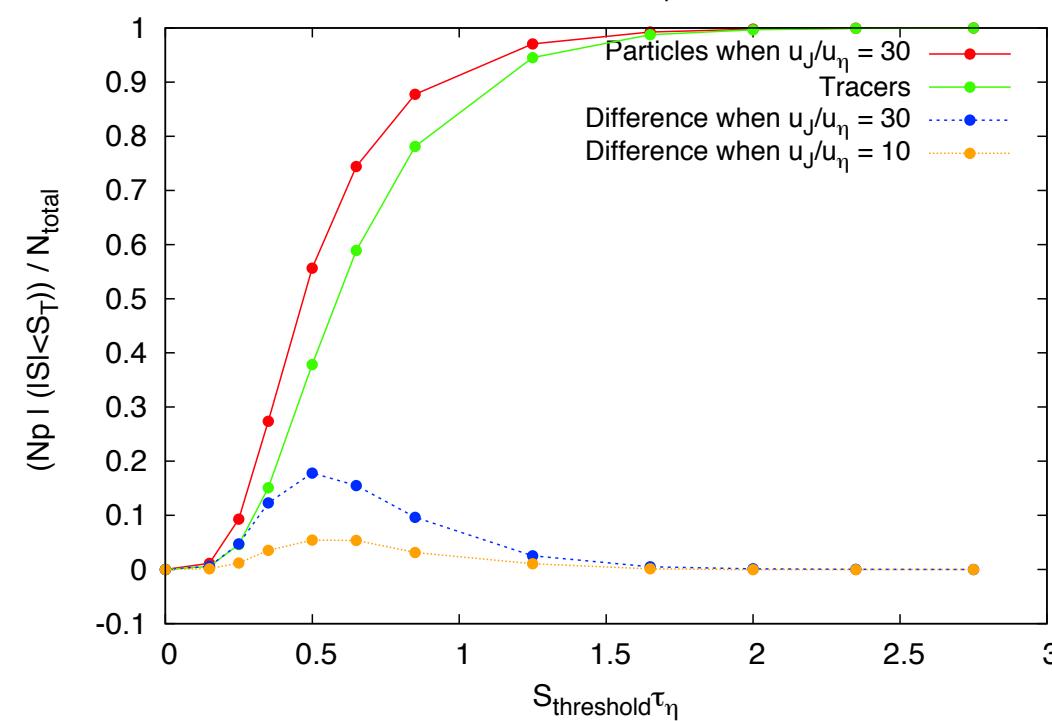
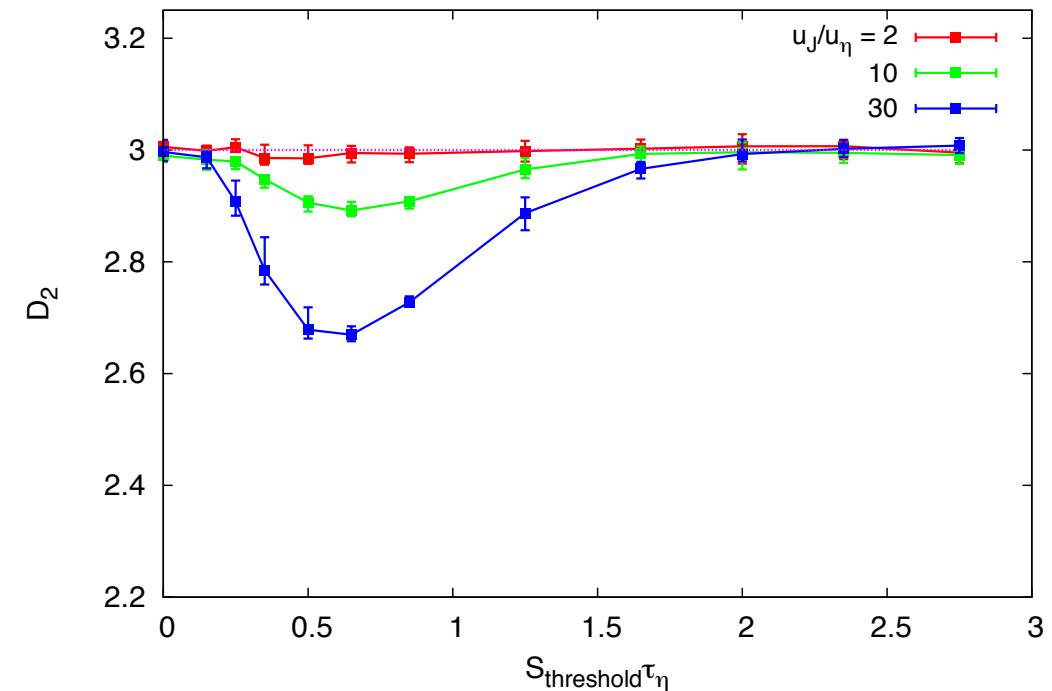
$$D_2 \approx 2$$



$$D_2 = 3$$

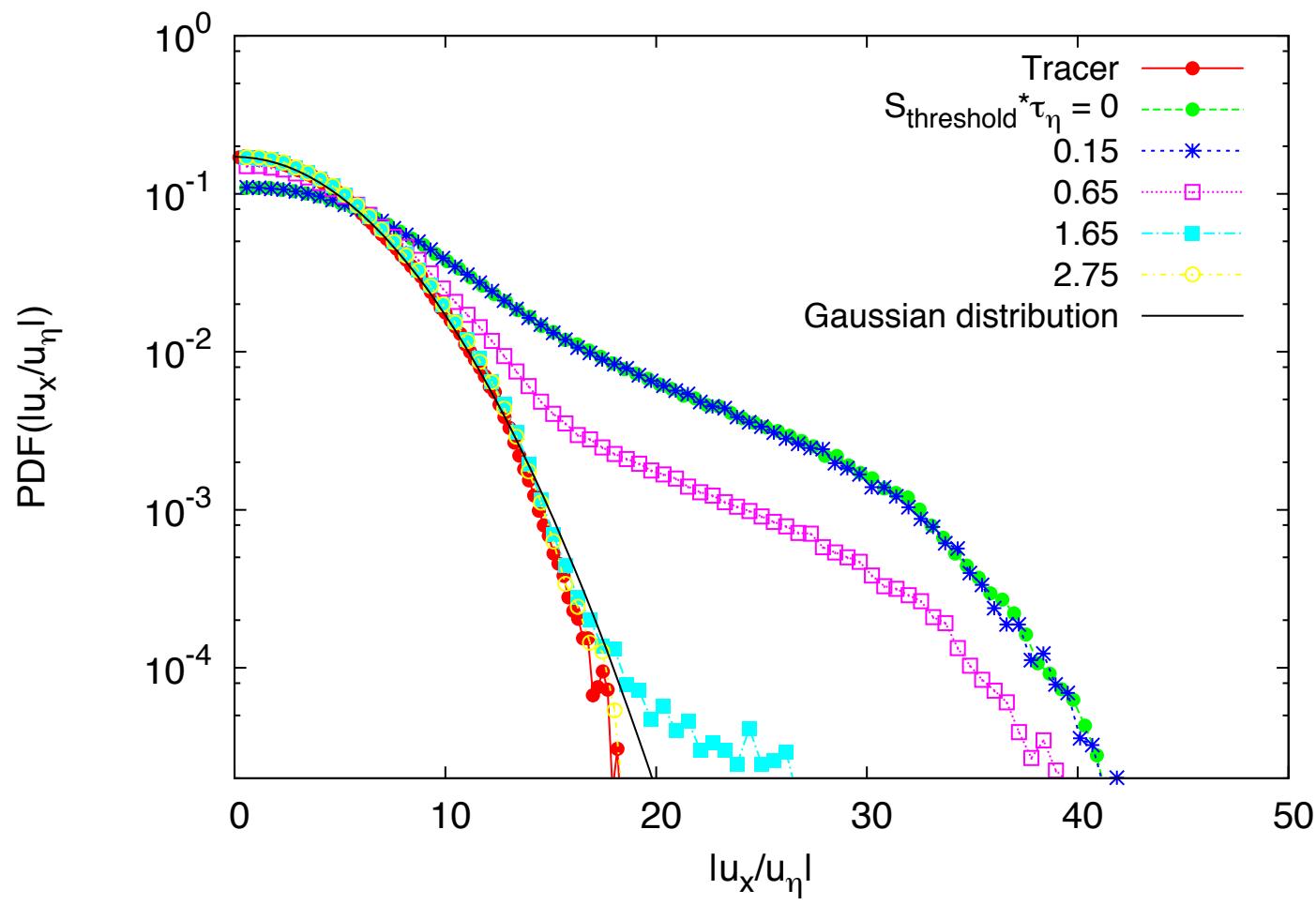
Analysis

Fractal dimension estimation as a function of the threshold value of the strain rate



Efficiency of the jump by considering the number of particles

Analysis

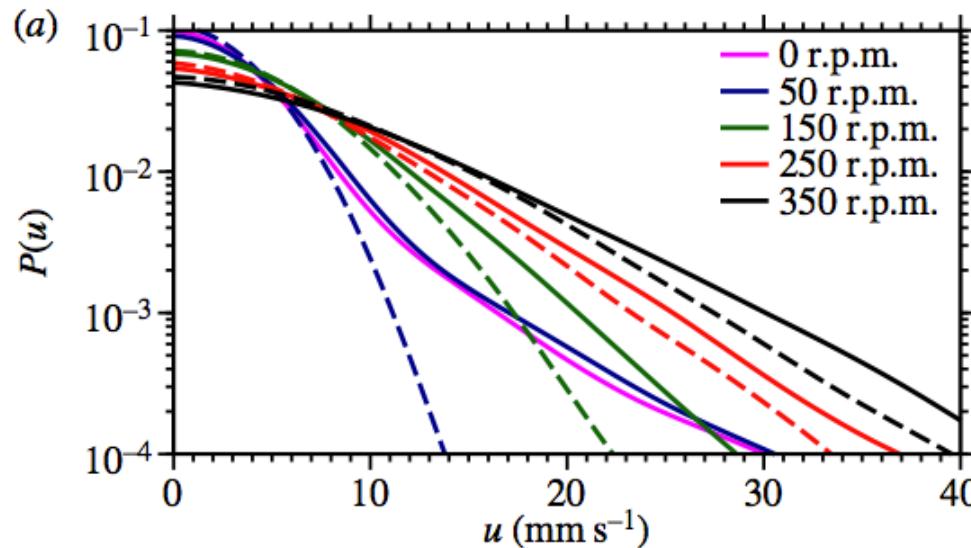


PDF of absolute value of single component velocity

Perspective

Collaboration with **Institute of Environmental Engineering**
ETH Zurich, Switzerland

François-Gaël Michalec, Markus Holzner



- Tune the model's parameters
- Predict the behavior

Thank you!